## Motor/Hollow Rotor Actuator Product Recommendation Information Sheet: Table Drive

Required Product Leave blank and send if you have no reques	St. We will call you back.		
□Induction Motor, Reversible Motor, Electromagnetic Brake Motor, etc. □ □Brushless Motor □Stepping Motor □Hollow Rotary Ac		otor □Speed	Control Motor and Inverter Packag
■ Drive Mechanism Specifications • Leave bla	ank and send if there is anything	g unclear. We will call y	rou back.
able Shape and Dimensions			Structure of Drive Mechanism
☐ Disk Type: Diameter ····· $\phi D =$	mm		
☐ Square Type: Length ······ A =	mm		<u>Load</u> <u>Tab</u>
Width B =	mm		Shaft Secondary Pulle
● Table Thickness ····· t =	mm		Transmission Belt Primary Pulle
● Table Mass or Material ····· m =	kg or material →		Mot
● Table Shaft Diameter ····· D₂ =	mm		Shape of Table
● Table Shaft Length ····· L =	mm		b the state of the
● Table Shaft Mass or Material ····· m₂ =	kg or material →		φDI A
nape of Load and Dimensions to be Indicated			
$\Box$ Cylinder Type: Diameter $\phi D_W = \phi$	mm	Shape of Load	
☐ Square Cylinder Type: Length ······ Aw =	mm		hw hw
Width $\cdots =$	mm		*
●Load Height······   hw =	mm		φDw Aw
● Load Mass or Material····· m =	kg or material →		are te te de la companya de la comp
● Load Rotation Radius······ r =	mm		
Number of Loads····· n =			
$lacktriangle$ Mechanism Inclination Angle $\cdots$ $\theta$ =	deg	Mec	hanism Angle $\frac{\theta}{\theta}$
ease indicate if using a connection belt pulley or gear. Not nece	essary if it's a direct c	onnection.	
Primary Pulley Diameter and Mass $\cdots$ $D_{P1} =$	mm $m_{P1} =$	kg	
When the mass is unknown, please enter the width and ma	aterial. $\rightarrow$ $L_{P1} =$	mm	Material:
Secondary Pulley Diameter and Mass. $D_{P2} =$	mm $m_{P2} =$	kg	
When the mass is unknown, please enter the width and ma	aterial. $\rightarrow$ $L_{P2} =$	mm	Material:
Operating Conditions • Leave blank and send if there is an	nything unclear. We will call you	back.	
Rotation Angle per Motion	° Traveling Speed	V	
<u> </u>			
	s	/   _	\ /
	s s	Trave	
$lacktriangle$ Desired acceleration and deceleration time (if any) $\cdots$ $t_7 = t_7$		Amount	[mm]
$lacktriangle$ Desired acceleration and deceleration time (if any) $t_1 = t_2 = t_3$ Stopping Time $t_2 = t_3$	s	/	[mm]
Desired acceleration and deceleration time (if any) $\cdots$ $t_1 = \cdots = 0$ Stopping Time $\cdots \cdots \cdots$	s s	Acceleration	Deceleration Time t.
Desired acceleration and deceleration time (if any) $\cdots$ $t_1$ = $\vdots$ Stopping Time $\cdots$ $t_2$ = $\vdots$ When speed is desired $\cdots$ $V$ = $\sim$ Stopping Accuracy $\cdots$ $\pm$ $\cdots$	s s	Acceleration Time t <sub>1</sub>	Deceleration Time t.
Desired acceleration and deceleration time (if any) $\cdots$ $t_1$ = $\vdots$ Stopping Time $\cdots$ $t_2$ = $\vdots$ When speed is desired $\cdots$ $V$ = $\sim$ Stopping Accuracy $\cdots$ $\pm$ $\odot$	s s r/min	Acceleration Time t <sub>1</sub>	Deceleration Time t:
Desired acceleration and deceleration time (if any) $\cdots$ $t_1$ = $\vdots$ Stopping Time $\cdots$ $t_2$ = $\vdots$ When speed is desired $\cdots$ $V$ = $\sim$ Stopping Accuracy $\cdots$ $\pm$ $\odot$	s s r/min	Acceleration Time t <sub>1</sub>	Deceleration Time t:
Desired acceleration and deceleration time (if any) $\cdots$ $t_1$ = $t_2$	s s r/min	Acceleration Time t  Positioning	Deceleration Time to [S]  Stopping Time to [S]
Desired acceleration and deceleration time (if any) $\cdots$ $t_1$ = $t_2$ = $t_2$ = $t_2$ = $t_2$ = $t_2$	s s r/min °	Acceleration Time t  Positioning	Deceleration Time to [S]  Stopping Time t2 [S]
Desired acceleration and deceleration time (if any)····       t₁ =         Stopping Time·····       t₂ =         When speed is desired·····       V = ~         Stopping Accuracy·····       ±         Power Supply Voltage····       Phase V,    Customer Information Company:	s s r/min Hz  E-mail:	Acceleration Time t  Positioning	Deceleration Time to [S]  Stopping Time t2 [S]
Desired acceleration and deceleration time (if any) $t_1 = t_2 = t_3$ Stopping Time $t_2 = t_4$ When speed is desired $t_4 = t_5$ Stopping Accuracy $t_5 = t_6$ Power Supply Voltage Phase V,  Customer Information  Company:  Department and Title:	s s r/min Hz  E-mail:	Acceleration Time ts Positioning	Deceleration Time to [S]  Stopping Time to [S]
Desired acceleration and deceleration time (if any) ··· t₁ = stopping Time ··· t₂ = stopping Time ··· t₂ = stopping Accuracy ··· t₂ = ·· Stopping Accuracy ··· t₂ = ·· Stopping Accuracy ··· t₂ = ·· Phase V, ··· Phase V, ··· Customer Information  Company:  Department and Title:  Name:	S S T/min Hz  E-mail:  Application:	Acceleration Time ts Positioning  Date:	Deceleration Time to Stopping Time to [S]  Year Month Day
Desired acceleration and deceleration time (if any) ··· t₁ =	E-mail: Application: Number of Units	Acceleration Time ts Positioning  Date:	Deceleration Time to Stopping Time to [S]  Year Month Day

HP

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